Distributional Smoothing with Virtual Adversarial Training, Adversarial Training Methods for Semi-Supervised Text Classification

Miyato et al., ICLR 2016, 2017

Outline

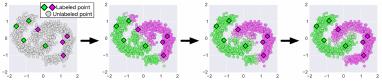
- Semi-supervised learning
 - Small set of labeled + large set of unlabeled data
 - Supervised + unsupervised learnings
 - ★ using pretrained word embeddings is implicitly semi-supervised learning
 - High performance with few labeled data
 - \star SOTA on IMDB, BERT-finetune, 200 vs 25000 labeled \sim 95.8%
 - Consistency regularization and data augmentation
- Adversarial examples
- Virtual adversarial examples (this work)
- (Virtual) adversarial embeddings (this work)
 - one of few data augmentation methods for NLP,
 - internal rather external, no changes in context words
 - can improve performances of many NLP tasks, already text classification and relation extraction
- Benefits of (virtual) adversarial embeddings (this work)
 - encouraging generalization
 - Improving semantics of word embeddings while learning the task
- Experimental results on IMDB dataset

Consistency Regularization and Data Augmentation

Consistency regularization

$$L(\boldsymbol{x}_{l}, y_{l}; \theta) = \mathcal{H}(q(y_{l} | \boldsymbol{x}_{l}), p(y | \boldsymbol{x}_{l}; \theta))$$
$$L_{c}(\boldsymbol{x}_{\mathrm{ul}}; \theta) = \mathrm{KL}(p(y | \boldsymbol{x}_{\mathrm{ul}}; \theta), p(y | \boldsymbol{x}_{\mathrm{ul}}^{+}; \theta))$$

- regularize the model to produce similar output distributions for both original input x and augmented input x^+ (x^+ has to be "close" to x in input space)
- \blacktriangleright labels are not needed for this regularizer term \rightarrow it suits semi-supervised learning
- intuitively,
 - the model assumes pseudo-labels for unlabeled data and force its augmentation to match its output distribution
 - ★ labels are propagated from labeled to unlabeled examples



- Two ways of generating x^+
 - ► Model's internal stochasticity: ∏-Model. Mean Teacher. ICT

Adversarial Examples

Adversarial examples:

$$L(\boldsymbol{x}_l, y_l; \theta) = \mathcal{H}(q(y_l | \boldsymbol{x}_l), \ p(y | \boldsymbol{x}_l; \theta))$$
$$\boldsymbol{\delta} = \operatorname{argmax}_{\boldsymbol{\delta} \in \mathcal{S}} L(\boldsymbol{x}_l + \boldsymbol{\delta}, y_l; \theta)$$

• find perturbation δ that changes the model's prediction, i.e., maximize the model's loss on given labeled input x_l

 $\star \ x_{\mathsf{adv}} = x_l + \delta$ is the resulted adversarial example

 control perturbation so that the adversaries are "close" to original example by a constraint S, e.g., l₂-ball

 \star adversarial examples fit in the consistency regularization approach

• Approximate solution $(S = l_2)$: gradient descent

$$oldsymbol{\delta} = -\epsilon rac{oldsymbol{g}}{\|oldsymbol{g}\|_2}, ext{ where } oldsymbol{g} =
abla_x L(oldsymbol{x}_l, y_l; heta)$$

Virtual Adversarial Examples (this work)

• Adversarial examples

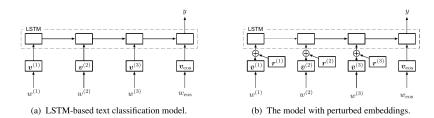
$$L(\boldsymbol{x}_l, y_l; \theta) = \mathcal{H}(q(y_l | \boldsymbol{x}_l), \ p(y | \boldsymbol{x}_l; \theta))$$
$$\boldsymbol{\delta} = \operatorname{argmax}_{\boldsymbol{\delta} \in \mathcal{S}} L(\boldsymbol{x}_l + \boldsymbol{\delta}, y_l; \theta)$$

• Virtual adversarial examples

$$L_{c}(\boldsymbol{x}_{ul}; \theta) = \mathrm{KL}(p(y|\boldsymbol{x}_{ul}; \theta), \ p(y|\boldsymbol{x}_{ul}^{+}; \theta))$$
$$\boldsymbol{\delta} = \mathrm{argmax}_{\boldsymbol{\delta} \in \mathcal{S}} L_{c}(\boldsymbol{x}_{ul} + \boldsymbol{\delta}; \theta)$$

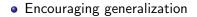
- \blacktriangleright similar to adversarial examples, find the perturbation δ that maximizes the consistency regularizer L_c instead
- labels are not needed
- $x^+ = x_{\mathsf{vadv}} = x_{ul} + \delta$ is the resulted virtual adversarial example

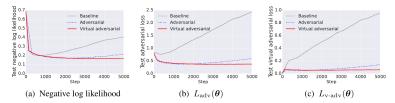
(Virtual) Adversarial Embeddings (this work)



- (Virtual) Adversarial Examples
 - Adversarial perturbation: small changes to real-valued inputs
- (Virtual) Adversarial Embeddings for NLP
 - \blacktriangleright issue: discrete inputs, series of high-dimensional one-hot vectors \rightarrow cannot directly compute perturbation
 - solution: compute perturbation on word embeddings instead of discrete word inputs

Benefits of (Virtual) Adversarial Embeddings





test loss consistently stays small

Benefits of (Virtual) Adversarial Embeddings

Improving semantics of word embeddings during learning the task

	'good'				'bad'			
	Baseline	Random	Adversarial	Virtual Adversarial	Baseline	Random	Adversarial	Virtual Adversarial
1	great	great	decent	decent	terrible	terrible	terrible	terrible
2	decent	decent	great	great	awful	awful	awful	awful
3	× <u>bad</u>	excellent	nice	nice	horrible	horrible	horrible	horrible
4	excellent	nice	fine	fine	×good	×good	poor	poor
5	Good	Good	entertaining	entertaining	Bad	poor	BAD	BAD
6	fine	$\times \underline{bad}$	interesting	interesting	BAD	BAD	stupid	stupid
7	nice	fine	Good	Good	poor	Bad	Bad	Bad
8	interesting	interesting	excellent	cool	stupid	stupid	laughable	laughable
9	solid	entertaining	solid	enjoyable	Horrible	Horrible	lame	lame
10	entertaining	solid	cool	excellent	horrendous	horrendous	Horrible	Horrible

- baseline is strongly influenced by the grammatical structure of language, but not by the semantics of the task.
 - ★ e.g., "bad" appears in the list of nearest neighbors of "good"
- (virtual) adversarial examples improve the word semantics
 - e.g., "bad" no longer appears in the 10 top nearest neighbors to "good", falling to the 19th nearest neighbor
 - (virtual) adversarial examples ensures that the meaning of a sentence cannot be inverted via a small change, so these words with similar grammatical role but different meaning become separated.

Experimental Results on IMDB Dataset

Method	Test error rate
Baseline (without embedding normalization)	7.33%
Baseline	7.39%
Random perturbation with labeled examples	7.20%
Random perturbation with labeled and unlabeled examples	6.78%
Adversarial	6.21%
Virtual Adversarial	5.91 %
Adversarial + Virtual Adversarial	6.09%
Virtual Adversarial (on bidirectional LSTM)	5.91%
Adversarial + Virtual Adversarial (on bidirectional LSTM)	6.02%
Full+Unlabeled+BoW (Maas et al., 2011)	11.11%
Transductive SVM (Johnson & Zhang, 2015b)	9.99%
NBSVM-bigrams (Wang & Manning, 2012)	8.78%
Paragraph Vectors (Le & Mikolov, 2014)	7.42%
SA-LSTM (Dai & Le, 2015)	7.24%
One-hot bi-LSTM* (Johnson & Zhang, 2016b)	5.94%

Thank you !